# Increased Safety in HDD Installations Using Bore Planning

Siggi Finnsson







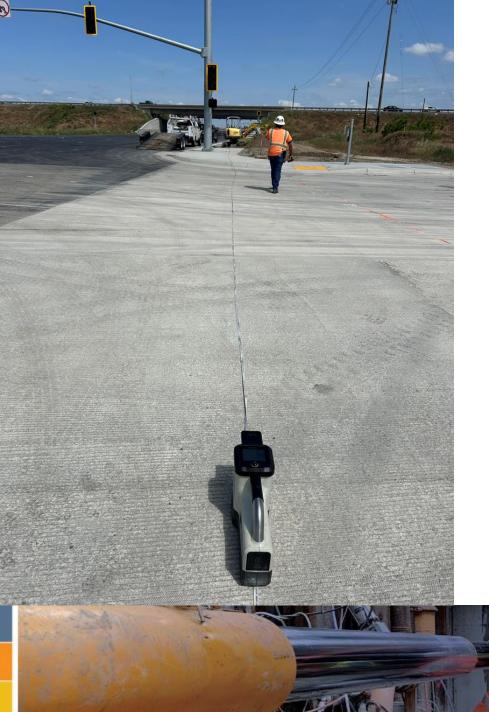
#### Overview

Bore planning in general

Benefits of a bore plan

Safety aspects of a bore plan

Concluding thoughts



# What is a bore plan?

- Everyone "plans", the definitions of a plan differ
- "Enter the ground here, come out over there, and stay around this depth"
- Comprehensive survey of the terrain, yielding a rod-by-rod plan
- Detailed survey with Geotech analysis, load and hydrofracture calculations



# What is a bore plan?

- For the purpose of this discussion, I will be focusing on bores done with a walkover locating system
- Comprehensive survey of the terrain, yielding a rod-by-rod plan



# Why are most bores drilled without a plan?

- Takes time
- Requires a survey of some sorts
- Engineers typically do bore planning
- Most jobs don't have the budget
- "I'm only going a few hundred feet and not very deep, I don't need a plan!"

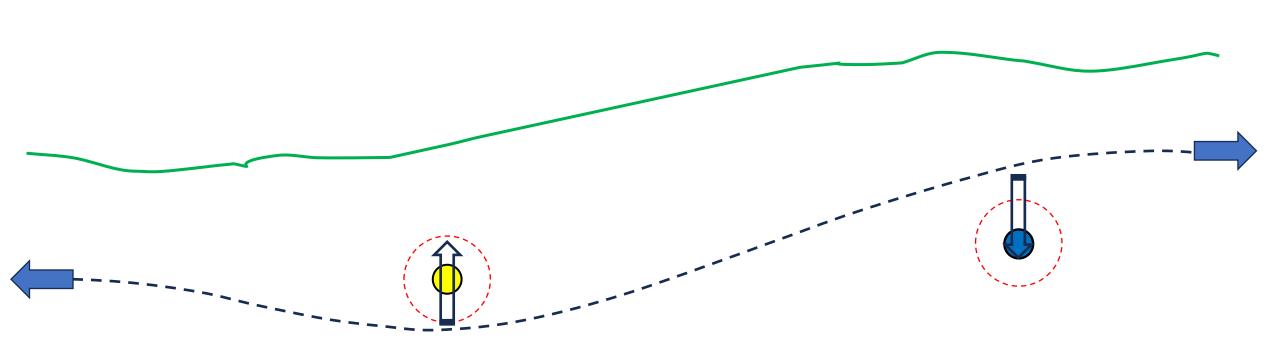


# Without a plan..

- Steering decisions more reactionary
- Changes in terrain often dictate the options
- Good clearance around utilities much more complicated
- A decision made a few rods ago can limit the steering options for the current rod
- Entire bore and all the obstacles and utilities are not accounted for
- Time spent deciding next steps



# Steering near a utility (reactive)

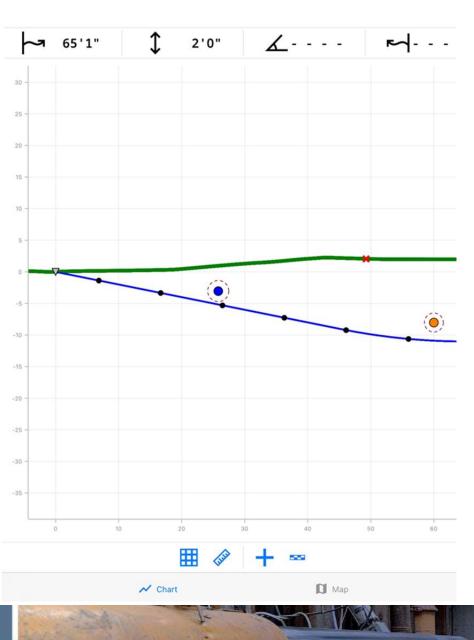






# Benefits of planning

- Provides entry-to-exit view
- Utility locations are translated from paint marks on the surface
- "What-if" scenarios can be run
- Underscores the relationship between the terrain, pitch changes, and resulting depths



# **∠** Benefits of planning

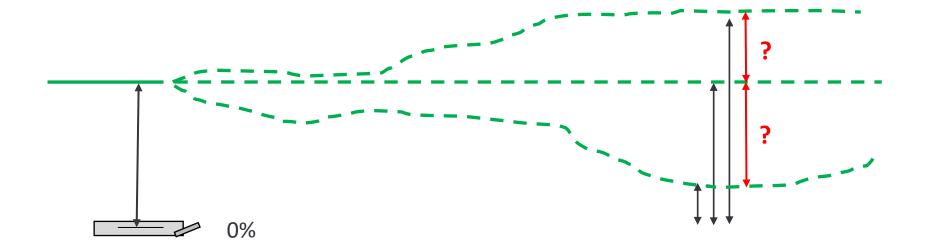
- Excellent training tool for green crews
- Increased productivity and elimination of guesswork
- Less wear and tear on the drill and drill pipe
- Reduction in other variable costs
- Better Product and more professionalism



# Some thoughts on depth in the context of walk-over locating

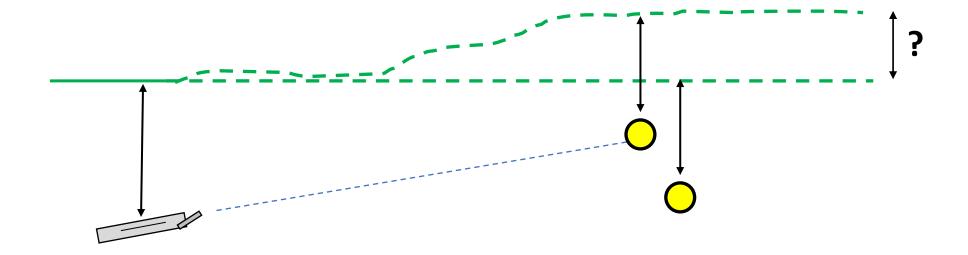
- Depth is referenced from the surface
- In HDD, typically means the drill head, utilities, or other points of interest
- Very difficult to know anything about depth changes without knowledge of the terrain

# **More on Depth**





# **More on Depth**







# Creating a plan involves...

- Surveying the terrain, identifying the entry and exit points
- Location and depth of utilities being crossed
- Establishing adequate clearance
- Drill parameters such a rod length, bend radius, entry and exit angles
- Location of waypoints
- Math





### One way to create a plan





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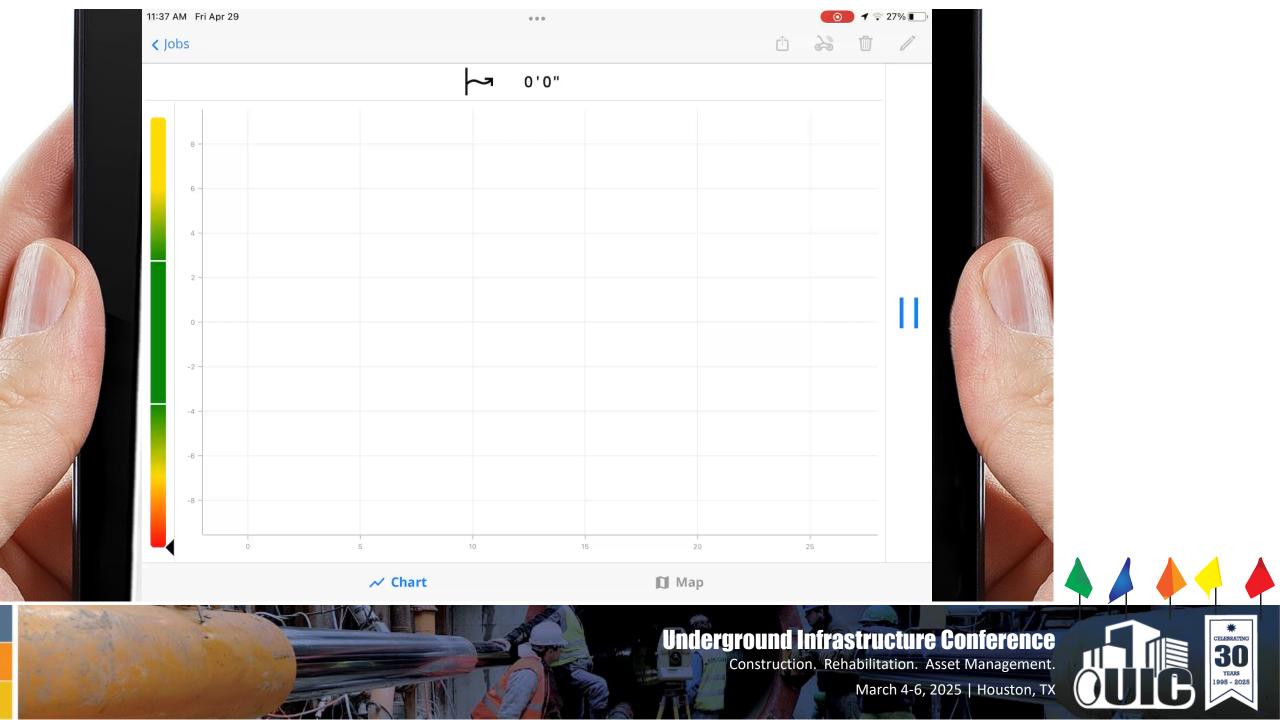






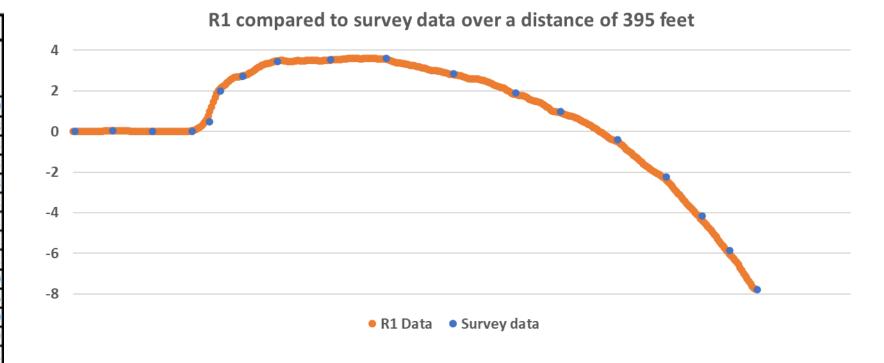
#### TeraTrak R1

- Advanced, easy-to-use measuring wheel and bore planning device
- Continuous plot of the elevations and distance in
   1-foot increments is created in real-time
- Data is streamed via Bluetooth to an iOS or Android smart device
- +/- 2" elevation accuracy over 500 ft
- Single path used for short (< 125 ft) drill calculations</li>



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|                    |                                 | _ |                    |                   |
|--------------------|---------------------------------|---|--------------------|-------------------|
|                    |                                 |   | IGO DATA           |                   |
| FROM<br>START (FT) | ELEV DIFF<br>FROM START<br>(FT) |   | FROM<br>START (FT) | ELEV DIFF<br>(FT) |
| 0.000              | 0.000                           |   | 0.00               | 0.0000            |
| 22.080             | 0.053                           |   | 0.04               | 0.0128            |
| 45.240             | 0.018                           |   | 0.01               | 0.0083            |
| 68.560             | -0.001                          |   | 0.04               | -0.0405           |
| 77.820             | 0.485                           |   | 0.72               | -0.2348           |
| 83.880             |                                 |   | 2.02               | -0.0172           |
| 96.580             |                                 |   | 2.71               | -0.0011           |
| 117.000            |                                 |   | 3.47               | -0.0261           |
| 147.950            | 3.533                           |   | 3.52               | 0.0131            |
| 179.950            | 3.616                           |   | 3.56               | 0.0560            |
| 218.920            |                                 |   | 2.82               | 0.0396            |
| 254.890            |                                 |   | 1.85               | 0.0470            |
| 281.010            |                                 |   | 0.94               | 0.0569            |
| 314.800            |                                 |   | -0.51              | 0.0972            |
| 341.830            |                                 |   | -2.30              | 0.0653            |
| 362.590            |                                 |   | -4.23              | 0.0623            |
| 378.790            |                                 |   | -5.94              | 0.0837            |
| 395.070            | -7.784                          |   | -7.76              | -0.0243           |



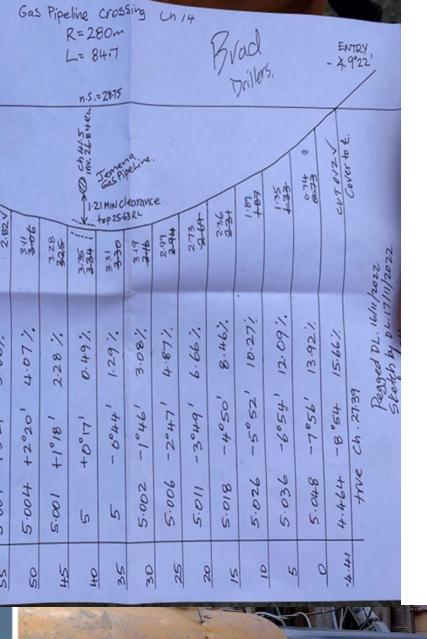


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celebrating



# Is the R1 accurate enough?

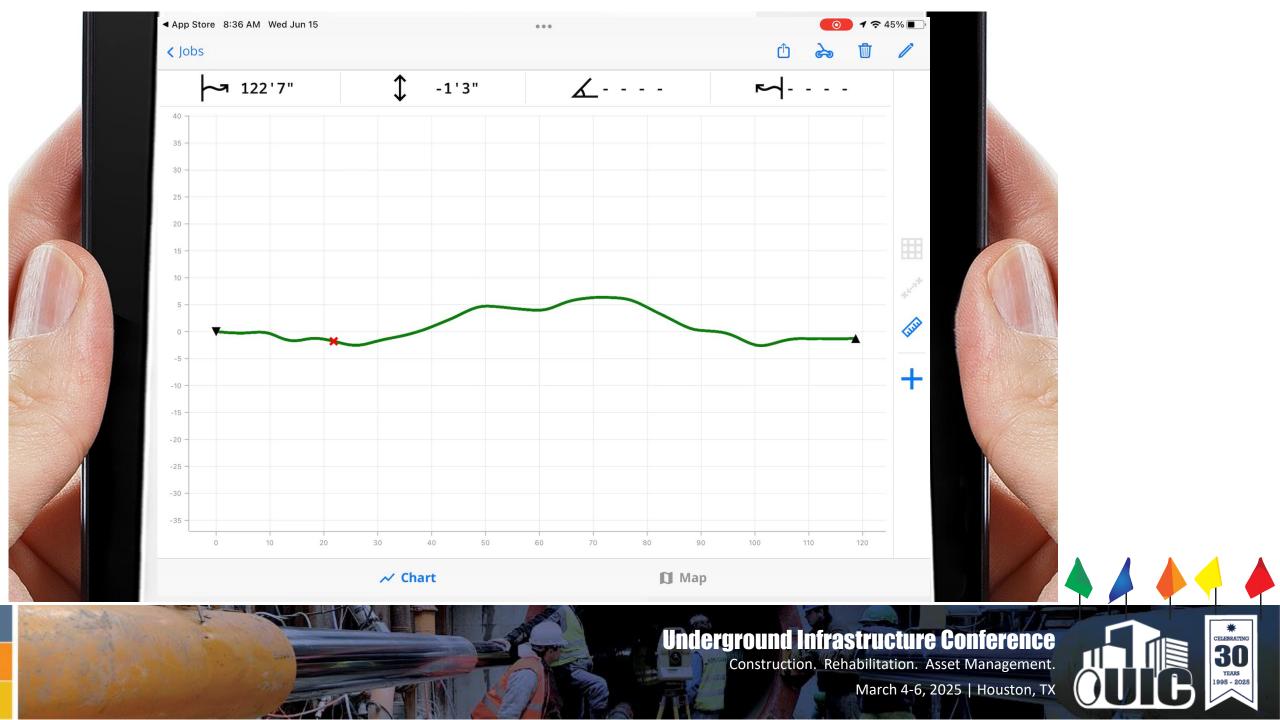
- Comparison to surveying equipment
- The R1 survey completed in about a ½-time
- The average difference between over 17 data points was 0.05 ft or 0.6 inches
- Largest difference: 0.23 ft
- Smallest difference: 0.001 ft



#### **Pre-bore Safety Aspects of a Bore plan**

- Requires all pertinent data for each step
- Holistic view of the terrain and the bore
- What and where are the obstacles
- Preferred path, i.e. above or below a given utility







# **Pre-bore Safety Aspects of a Bore plan**

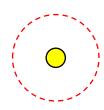
- Setback distance not sufficient, given the machine or bend radius constraints
- Combination of the terrain, setback distance and required depth and pitch may be incompatible
- Can result in the bore ending up being too close to an existing utility

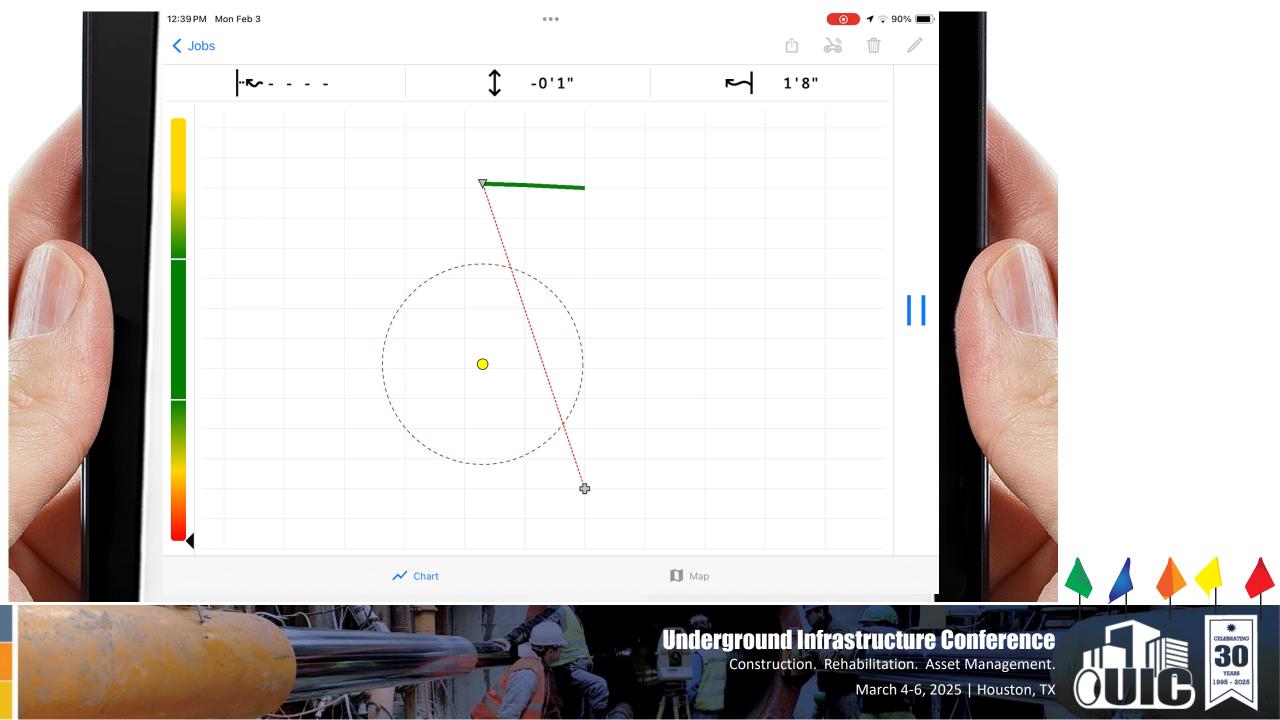


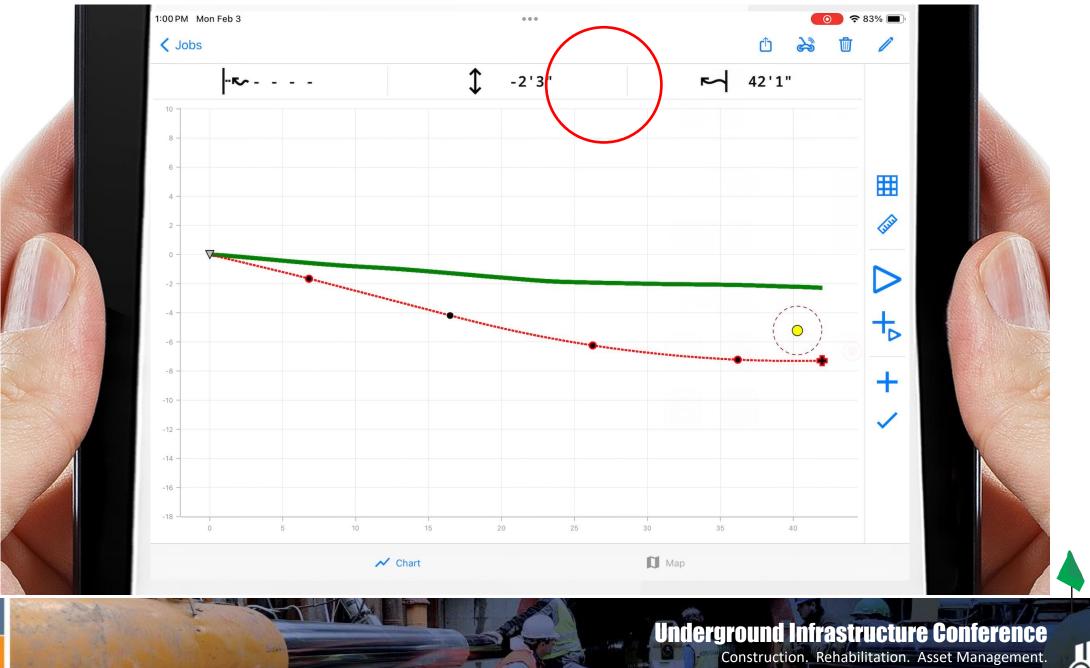
#### **Common case**

- Utility needs to be crossed, gas line at 36"
- The required clearance: 18"
- Planned entry is about 40 ft from the gas line,
- Elevation difference from entry to the gas line: unknown



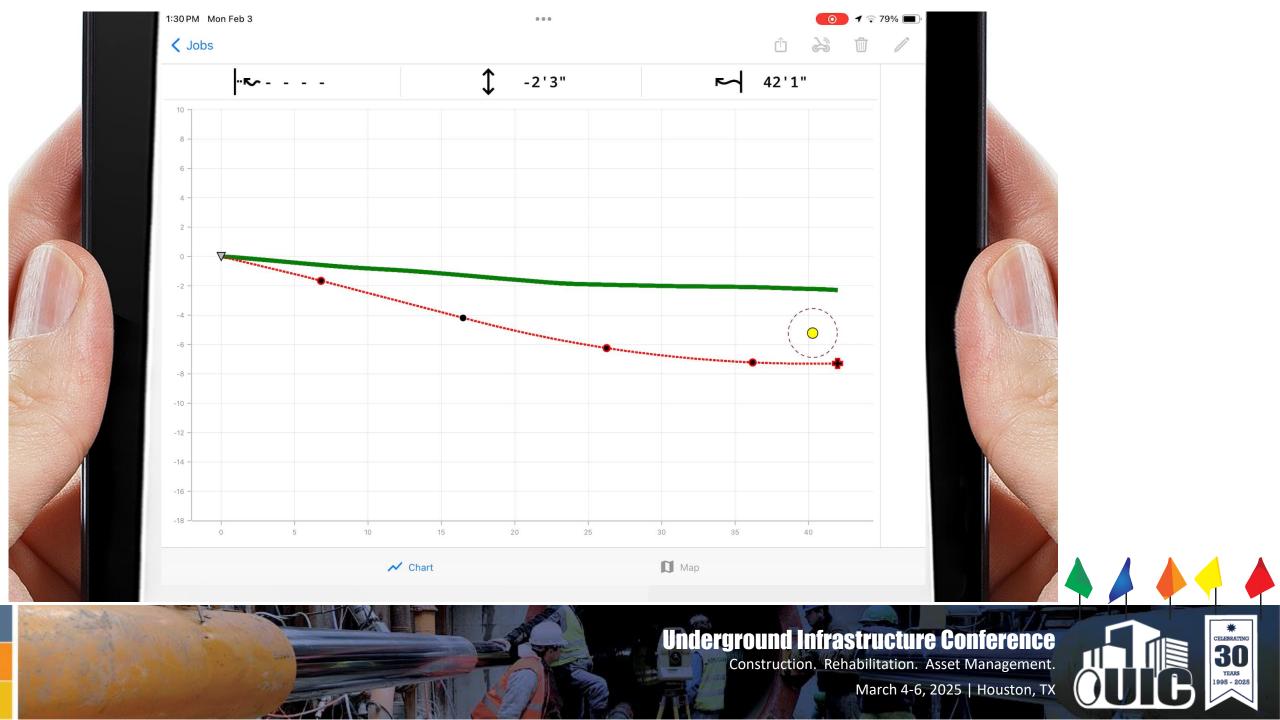






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#### Sample Standard Terrain V -24.0% (7' 0") -26.1% 3' 4" -37.1%(i) 5' 7" (10'0")7' 8" (10'0")-44.0% (10'0")-44.0% 10'0" (10'0")-44.0% 10'8" -44.0% 10'6" (10'0")(10'0")-44.0% 10'9" -44.0% (10'0")10' 8" -44.0% 9' 11" (10'0")✓ Chart

# **Pre-bore Safety Aspects of a Bore plan**

- What the crew has been asked to do isn't really (or not at all) achievable
- By choosing to go above the first utility it is impossible to go below the second one with adequate clearance
- Might be easier to drill the other direction
- Best tool to review required changes



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# Safety aspects of a plan during the bore

- Rod-by-rod plan based on an accurate survey of the terrain
- Targeted depth and pitch for each rod are known
- Utilities to be crossed have been daylighted and incorporated into the plan
- Crew has step-by-step instructions for navigation



# Safety aspects of a plan during the bore

- Proper interference investigation/mitigation
- Optimum frequencies chosen
- Locating system calibration has been verified
- Depth readings above ground have been checked
- Locating system accuracy is paramount



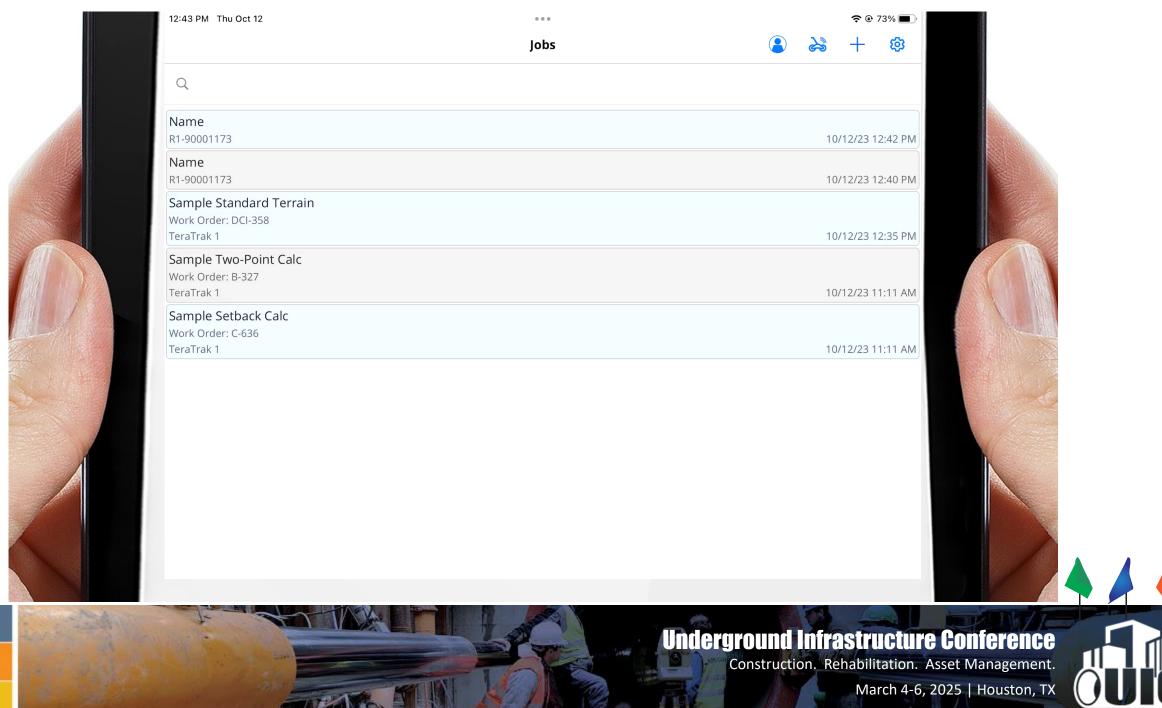
# What if the ground doesn't cooperate?

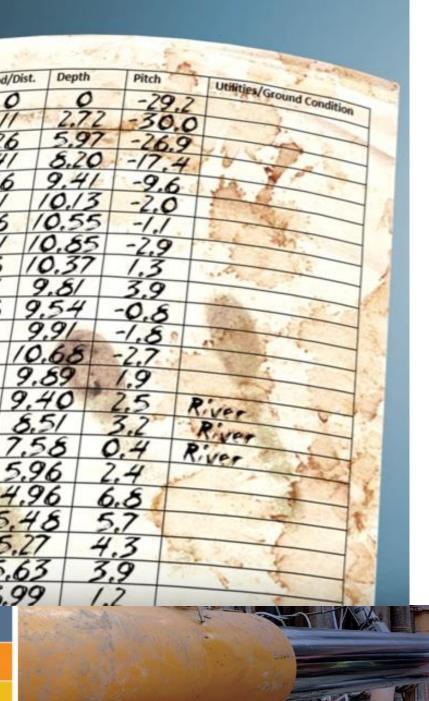
- Bore plan is the ideal mathematical solution
- Ground conditions do have a vote
- Inevitable deviations are highlighted
- Always a target of a desired depth and pitch for the next rod
- Simplified decision-making!



# Larger deviations or unexpected obstacles

- Deviation from plan becomes large enough to take several rods to get back on plan
- The plan could be modified
- Alternately creating a short "few-rod" plan to desired "future" location
- Obstacles often require a plan change
- The plan contains all the necessary data to do
   so





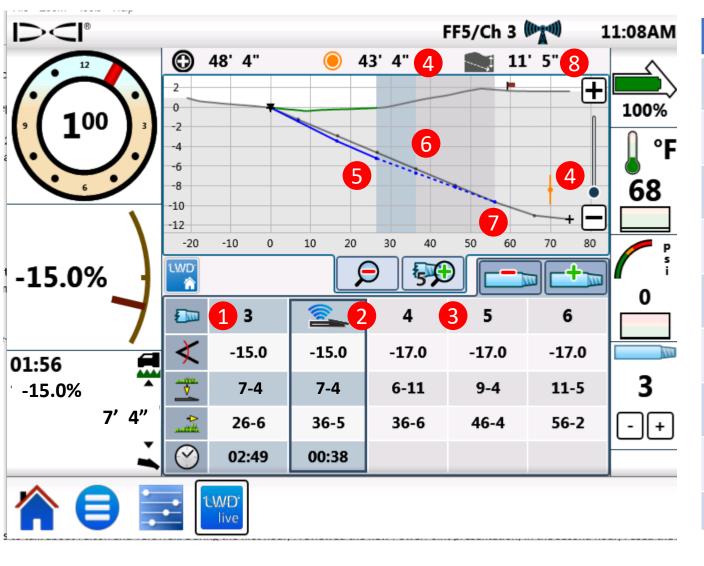
# **Keeping track of deviations**

- Locator should verify that the depth change matches change in pitch
- Write down actual values and compare to plan
- If pitch readings generally agree with the plan
   BUT the depth differs = warning
- Real-time tracking of plan versus actual is key



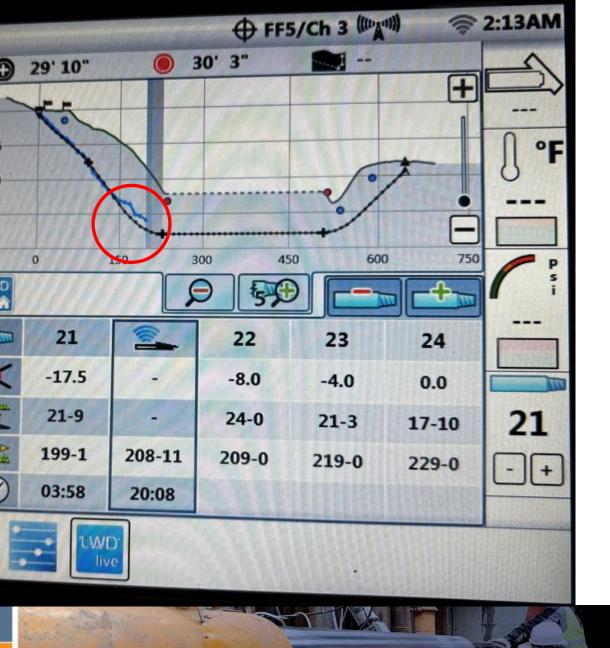
# **Remote integration**

- Currently, most rig operators rely on the locator for situational awareness
- Transferring the bore plan to the remote display, the operator has a comprehensive view of the bore ahead
- Viewing the rod-by-rod plan, and logging actual values, steering decisions are simplified



- 1 Logged data for rod 3
- 2 Current data
- 3 Next three rods of the plan
- 4 Distance to closest utility
- 5 Logged bore path (blue)
- 6 Planned path (grey)
- 7 3-rod projection at constant pitch
- 8 Estimated depth 3 rods out





### Real-world application

- 650 ft freeway crossing
- Terrain mapping took 20 minutes
- 15 ft depth required below the road
- Hardpan causes deviation
- 90 ft runway to get on to the plan
- Pilot bore completed in about 7 hrs



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# Remote Integration in summary

- Improved situational awareness
- Access to the rod-by rod plan
- Chart of planned and drilled paths
- View of obstacles and distances
- Easier to get back on plan



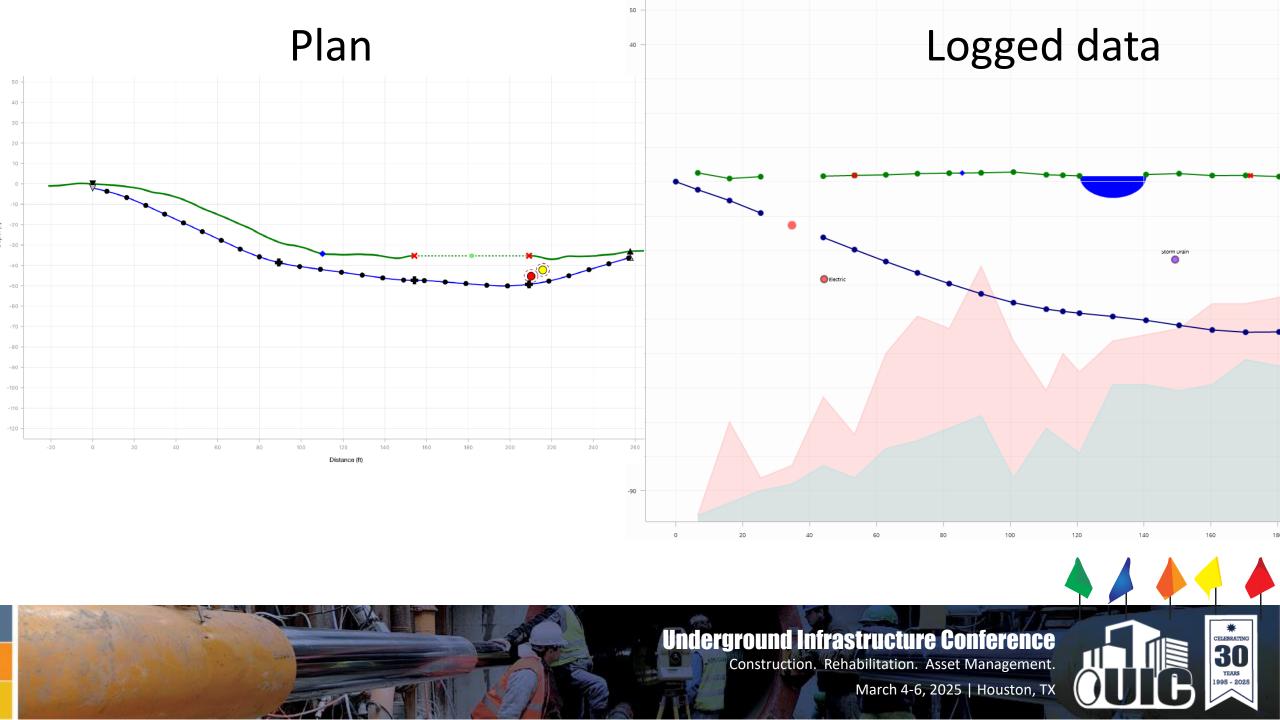
# Post-bore Safety Aspects of a Bore plan

- The plan documented the intended solution
- Basis for comparison to the installation
- Installation data can come from drill logs, which can be from field notes, logbooks, or other types of data logging



# Post-bore Safety Aspects of a Bore plan

- Modern systems support the logging of data
- The system used to navigate the pilot bore is the source of the drill data
- The output is generally in the same format as the plan, rod-by-rod data and a chart
- Allows comparison where "significant deviations" could result in further investigations or clarifications



|   |    |          | ✓      | <u> </u> |
|---|----|----------|--------|----------|
| + | 0  |          | -24.0% | 2' 1"    |
|   | 1  | (7' 0")  | -26.1% | 3' 4"    |
|   | 2  | (10' 0") | -37.1% | 5' 7"    |
|   | 3  | (10' 0") | -47.3% | 7' 9"    |
|   | 4  | (10' 0") | -47.3% | 10' 6"   |
|   | 5  | (10' 0") | -47.3% | 11' 6"   |
|   | 6  | (10' 0") | -47.3% | 11' 7"   |
|   | 7  | (10' 0") | -47.3% | 12' 1"   |
|   | 8  | (10' 0") | -47.1% | 12' 4"   |
|   | 9  | (10' 0") | -35.4% | 11'1"    |
| + | 10 | (9' 9")  | -24.8% | 9' 10"   |
|   | 10 | (0' 3")  | -24.6% | 9' 10"   |
|   | 11 | (10' 0") | -14.2% | 9' 8"    |
|   | 12 | (10' 0") | -14.2% | 7' 10"   |
|   | 13 | (10' 0") | -14.2% | 8' 9"    |
|   | 14 | (10' 0") | -14.2% | 10' 3"   |
|   | 15 | (10' 0") | -14.2% | 10' 7"   |
|   | 16 | (10' 0") | -5.2%  | 11' 3"   |
| + | 17 | (5' 3")  | 0.0%   | 12' 0"   |
|   | 17 | (4' 9")  | -4.8%  | 12' 2"   |
|   | 18 | (10' 0") | -7.8%  | 12' 11"  |
|   | 19 | (10' 0") | -7.8%  | 13' 8"   |
|   | 20 | (10' 0") | -7.8%  | 14' 6"   |

| 0                                     | ₹ -46.0%          |                  |  |  |  |
|---------------------------------------|-------------------|------------------|--|--|--|
|                                       | $\overline{\psi}$ | ⇒0' 0"           |  |  |  |
| 1                                     | ⊄ -26.5%          |                  |  |  |  |
|                                       | <b>√4'11"</b>     | <b>⇒6' 7"</b>    |  |  |  |
| 2                                     | ⊄ -40.0%          |                  |  |  |  |
|                                       | <b>√6'5"</b>      | ⇒16' 1"          |  |  |  |
| 3                                     | ⊄ -38.0%          |                  |  |  |  |
|                                       | <b>√10'7"</b>     | <b>⇒</b> 25' 5"  |  |  |  |
| 4                                     | ≮                 |                  |  |  |  |
| 4                                     | $\downarrow$      | →34' 9"          |  |  |  |
| 5                                     | ⊄ -38.0%          |                  |  |  |  |
|                                       | <b>√17'10"</b>    | →44' 1"          |  |  |  |
| 6                                     | ⊄ -38.0%          | PC               |  |  |  |
| 0                                     | <b>√21'7"</b>     | <b>⇒</b> 53' 5"  |  |  |  |
| 7                                     | ⊄ -36.0%          |                  |  |  |  |
| , , , , , , , , , , , , , , , , , , , | <b>√25'3"</b>     | <b>→</b> 62' 10" |  |  |  |
| 8                                     | ⊄ -34.0%          |                  |  |  |  |
|                                       | <b>√28' 11"</b>   | →72' 3"          |  |  |  |
| 9                                     | ⊄ -32.0%          | <b>P</b> C       |  |  |  |
|                                       | <b>√32' 2</b> "   | →81'9"           |  |  |  |
| 10                                    | ⊄ -30.0%          |                  |  |  |  |
|                                       | √35' 3"           | →91'4"           |  |  |  |
| 11                                    | ⊄ -23.5%          |                  |  |  |  |
|                                       | <b>√38' 1"</b>    | →101'0"          |  |  |  |
| 12                                    | ⊄ -15.0%          |                  |  |  |  |
|                                       | <b>√39' 2"</b>    | →110'9"          |  |  |  |
| 12½                                   | ⊄ -11.0%          |                  |  |  |  |
|                                       | √39' 8"           | →115' 9"         |  |  |  |
| 13                                    | ⊄ -10.5%          |                  |  |  |  |
|                                       | <b>√40'0"</b>     | →120' 9"         |  |  |  |
|                                       |                   |                  |  |  |  |











#### **Conclusions**

- Plan forces all the pertinent data to be gathered and considered
- "What if" scenarios can be explored, resulting in the best option
- Reduced decision load during installation
- Deviations dealt with more simply
- Safety is at the forefront
- The final product is much better



### **Questions?**

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